Chapter Four "Force System Resultants"

CHAPTER OBJECTIVES

■ to discuss the concept of the moment of a force and show how to calculate it in two and three dimensions.

■ to provide a method for finding the moment of a force about a Specified axis.

Ito define the moment of a couple.

1. Moment of a Force- Scalar Formulation

When a force is applied to a body it will produce a tendency for the body to rotate about a point that is not on the line of action of the force. This tendency to rotate is sometimes called a *torque*, but most often it is called the *moment of a force* or *simply the moment*.





 $d' = d \sin \theta$



Mo=0

Mo=F.d[′]=F.d.sinO





Resultant Moment

$$\zeta + (M_R)_o = \Sigma F d;$$
 $(M_R)_o = F_1 d_1 - F_2 d_2 + F_3 d_3$

Example -1:For each case illustrated, determine the moment of the force about point O.

$$\zeta + (M_R)_o = \Sigma F d;$$
 $(M_R)_o = F_1 d_1 - F_2 d_2 + F_3 d_3$

 $M_0=F. d = -100*2=-200 N.m$

$$M_0=F. d = -50*0.75 = -37.5 N.m$$

Mo=F. d = $-40 * (4 + 2 * \cos 30^{\circ}) = -229.28$ Ib.ft

Mo=F. d = $60 * (1 \sin 45^{\circ}) = 42.426$ Ib.ft

Mo=F. d =7*(4-1)= 21kN.m





100 N







Example -2:

Determine the resultant moment of the three forces acting on the rod shown in Fig. 4–5 about point O.

Ans:

$$\zeta + (M_R)_o = \Sigma Fd;$$
 $(M_R)_o = F_1 d_1 - F_2 d_2 + F_3 d_3$
 $= -600 * 1 - 300 * 2.5 \sin 45 + 500(1 + 2 + 2.5 \cos 45)$

2. Principle of Moments

Varignon's theorem: the moment of a force about a point is equal to the sum of the moments of the components of the force about the point.

$$M_O = F_x y - F_y x$$





Example -3:Determine the moment of the force a about point O.



Problems:

1.Force F acts at the end of the angle bracket. Determine the moment of the force about point O.



2- Determine the moment of the force about point O. Neglect the thickness of the member in figures ::



