

Lecture7: Travelling wave solution

One of the cornerstones in the study of both linear and nonlinear PDEs is the wave propagation. A wave is a recognizable signal which is transferred from one part of the medium to another part with a recognizable speed of propagation. Energy is often transferred as the wave propagates, but matter may not be. We mention here a few areas where wave propagation is of fundamental importance.

- * Fluid mechanics (water waves, aerodynamics)
- * Acoustics (sound waves in air and liquids)
- * Elasticity (stress waves, earthquakes)
- * Electromagnetic theory (optics, electromagnetic waves)
- * Biology (epizootic waves)
- * Chemistry (combustion and detonation waves)

The simplest form of a mathematical wave is a function of the form

$$u(x,t) = f(\eta), \quad \eta = x - \mu t \quad (19)$$

where $\mu > 0$ is constant (speed of travelling waves). This function is transform the PDE into ODE with one independent variable like the similarity transform.

Example: Find travelling wave solutions to the wave equation

$$u_{tt} = a^2 u_{xx}, \quad x \in \mathbb{R}, t > 0, \quad (20)$$

with boundary conditions $u(-\infty, t) = \text{const.}$, $u(+\infty, t) = \text{const.}$

Inserting $u(x,t) = f(x - \mu t)$, into the wave equation, we find

$$u_{tt} - a^2 u_{xx} = \mu^2 f'' - a^2 f'' = (\mu^2 - a^2) f'' = 0 \quad (21)$$

so that either $f(\eta) = A + B\eta$ for some constants A, B or $\mu = \pm a$ and f arbitrary. In the first case we would have

$$u(x,t) = A + B(x \pm at)$$

but the above boundary conditions cannot be satisfied unless $B = 0$. Thus, the only travelling wave solution in this case is constant. For the other case, we see that clearly for any twice differentiable function f such that

$\lim_{\eta \rightarrow \pm\infty} f = d_{\pm\infty}$ the solution

$$u(x,t) = f(x \pm at)$$

is a travelling wave solution (a pulse if $d_{+\infty} = d_{-\infty}$). In general, it follows that any solution to the wave equation can be obtained as a superposition of two travelling waves: one to the right and one to the left

$$u(x,t) = f(x-a) + g(x+at). \quad (22)$$

Not all equations admit travelling wave solutions, as demonstrated below.

Example: Consider the diffusion equation

$$u_t = Du_{xx}, \quad x \in R, t > 0 \quad (23)$$

Substituting the travelling wave formula $u(x,t) = f(x-\mu t)$, we obtain

$$-\mu f' - Df'' = 0$$

that has the general solution $f(\eta) = a + be^{-\frac{\mu\eta}{D}}$.

It is clear that for f to be constant at both plus and minus infinity it is necessary that $b=0$. Thus, there are no nonconstant travelling wave solutions to the diffusion equation.

We have already seen that the non-viscid Burger's equation

$$u_t + uu_x = 0, \quad x \in R, t > 0 \quad (24)$$

does not admit a travelling wave solution: any profile will either smooth out or form a shock wave (which can be considered as a generalized travelling wave - it is not continuous!). However, some amount of dissipation represented by a diffusion term allows to avoid shocks.

Example: Find travelling wave solutions of the Burger's equation with viscosity

$$u_t + uu_x = \nu u_{xx}, \quad x \in R, t > 0 \quad (25)$$

for $u \rightarrow u_1$, as $x \rightarrow -\infty$, $u \rightarrow u_2$, as $x \rightarrow +\infty$ and $u_1 > u_2$. The term uu_x will have a shocking up effect that will cause waves to break and the term νu_{xx} is a diffusion like term.

substituting $u(x,t) = f(\eta)$, $\eta = x - \mu t$ to Burgers' equation, we have

$$-\mu f' + ff' - \nu f'' = 0$$

we re-write this equation as

$$-\mu f' + \frac{1}{2}(f^2)' - \nu f'' = 0$$

hence we can integrate getting

$-\mu f + \frac{1}{2}f^2 - \nu f' = B$, where B is a constant of integration. Hence

$$\frac{df}{d\eta} = \frac{1}{2\nu}(f^2 - 2\mu f - 2B) \quad (26)$$

Ex1: find the solution of this ODE(26)? ((H.W))

Ex2: Find travelling wave solutions of the KdV equation

$$u_t + uu_x + u_{xxx} = 0, \quad x \in \mathbb{R}, t > 0, \text{ with } \lim_{x \rightarrow \pm\infty} u = 0, \lim_{x \rightarrow \pm\infty} u' = 0$$

$$\lim_{x \rightarrow \pm\infty} u'' = 0 \quad ((H.W))$$

Transformations: change of variables may linearize the systems of non-linear PDEs or reduce the non-linear PDE to a non-linear ODE. These change can be classified into three group: transformation of only the dependent variable, transformation of only the independent variable and transformation of both dependent and independent variables(mixed).