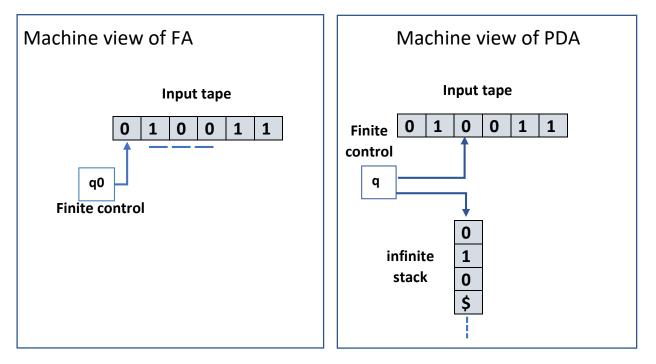
## Push down automata (PDA)



A more powerful machine:

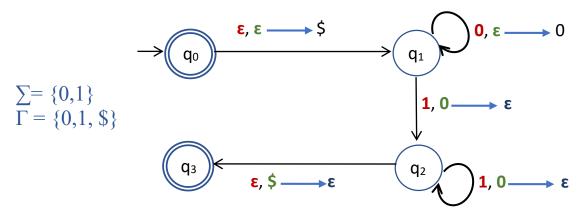
- Limitation of FA related to fact that they can only "remember" a bound amount of information.
- What is the simplest alteration that adds unbounded "memory" to our machine?
- Should be able to recognize, e.g,  $\{0^n1^n:n \ge 0\}$

<u>PDF diagram</u> Tape alphabet  $\sum$ Stack alphabet  $\Gamma = \sum$  and \$

## Two ways to describe PDF

- 1. Diagram
- 2. Formal definition

Example1: PDA



Note: transition label: (tape symbol read, stack symbol popped → stack symbol pushed)

Taking a transition labelled:



a ∈ (∑ U {**ɛ**}) b, c ∈ (Γ U {**ɛ**})

If the input symbol is a and the pop stack is b then q1 to q2, pop b, push c, advance read head

- read a from tape, or don't read from tape if a= ε
- pop b from stack, or don't pop from stack if b= ε
- push c onto stack, or don't push onto stack if c= ε

> In example 1 recognize  $L = \{0^n 1^n : n \ge 0\}$ 

:. Tape: 0011 is accept but 001 is not.

**Theory of Computation** 

**Push Down Automata (PDA)** 

## The formal definition of PDA

A PDA is a 6-tuple (Q,  $\Sigma$ ,  $\Gamma$ ,  $\delta$ , S, F) where:

- Q is a finite set called the states.
- $\sum$  is a finite set called the tape alphabet
- Γ is a finite set called the stack alphabet
- $\delta: Q \ge (\Sigma \cup \{\epsilon\}) \ge (\Gamma \cup \{\epsilon\}) \rightarrow \delta(Q \ge (\Gamma \cup \{\epsilon\}))$  is a function called the transition function
- S is an element of Q called the start state
- F is a subset of Q called the accepted states
- PDA M= (Q,  $\Sigma$ ,  $\Gamma$ ,  $\delta$ , S, F) accepts string w  $\in \Sigma^*$  if w can be written as  $w_1 w_2 w_3 \dots w_m \in (\sum U \{\epsilon\})^*$ , and there exist states  $r_0 r_1 r_2 \dots r_m$  and there exist strings  $s_0 s_1 s_2 \dots s_m$  in  $(\Gamma U \{\epsilon\})^*$ 
  - $r_0 = q_0$  and  $s_0 = \varepsilon$
  - $(\mathbf{r}_{i+1}, \mathbf{b}) \in \delta(\mathbf{r}_i, \mathbf{w}_{i+1}, \mathbf{a})$ , where  $\mathbf{s}_{i=1} = \mathbf{a}_t$ ,  $\mathbf{s}_{i+1} = \mathbf{b}_t$  for some  $t \in \Gamma^*$

Example 1 in formal definition:

 $M = \langle Q, \Sigma, \Gamma, S, F, \delta \rangle$  $Q = \{q_0, q_1, q_2, q_3\}$  $\Sigma = \{0, 1\}$  $\Gamma = \{0, 1, \$\}$  $S = q_0$  $F = \{q_0, q_3\}$ 

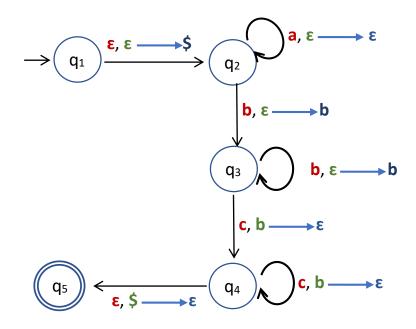
- $\delta(q_0, \varepsilon, \varepsilon) = \{(q_1, \xi)\}$   $\delta(q_1, 0, \varepsilon) = \{(q_1, 0)\}$   $\delta(q_1, 1, 0) = \{(q_2, \varepsilon)\}$   $\delta(q_2, 1, 0) = \{(q_2, \varepsilon)\}$   $\delta(q_3, \varepsilon, \xi) = \{(q_2, \varepsilon)\}$

**Theory of Computation** 

## Example 2:

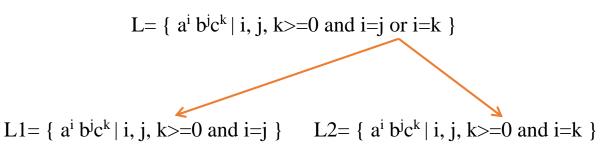
L= {  $a^i b^j c^k$  | i, j, k>=0 and j=k}

Solution:

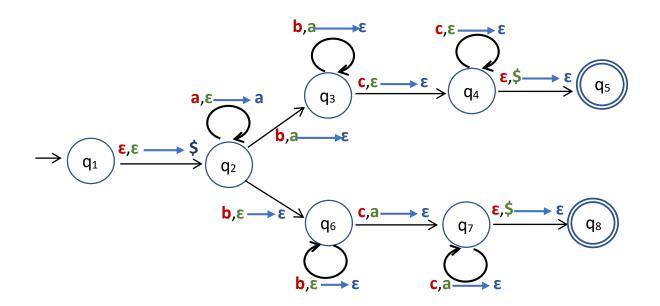


Example 3:

Construct a PDA for language

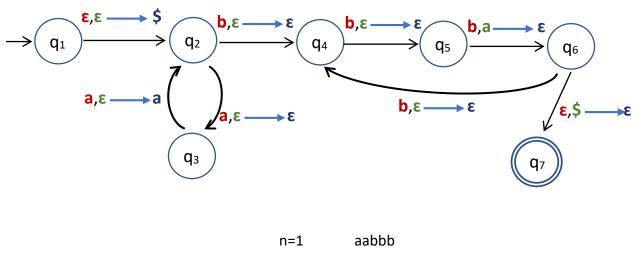


$$L=L1 U L2$$



Example 4:

Construct a PDA for language L= $\{a^{2n}b^{3n}|n>=1\}$ 



- n=2 aaaabbbbbb
- n=3 aaaaaabbbbbbbbb