

ALGEBRAIC TOPOLOGY

Prof. Dr. Hana' M. Ali

Lecture 2

HOMOTOPY

Definition:

Two continuous maps $f, g: X \rightarrow Y$ from a topological space X into a topological space Y , are said to be homotopic and denoted by $f \simeq g$ if, there exists a continuous map $H: X \times I \rightarrow Y$, where $I = [0,1]$ is the unit interval, satisfied for every $x \in X$:

- $H(x, 0) = f(x)$;
- $H(x, 1) = g(x)$.

We call H a *homotopy* from f to g and denoted by $H: f \simeq g$.

Note:

To better visualize the geometric content of the definition:

- ✓ Write $H_t(x) = H(x, t)$, for any $(x, t) \in X \times I$.
- ✓ Then $H_t: X \rightarrow Y$ is a continuous map s.t. $H_0 = f$ and $H_1 = g$.
- ✓ We usually think of the parameter $t \in I$ as time and the homotopy H_t as a continuous deformation of a map.

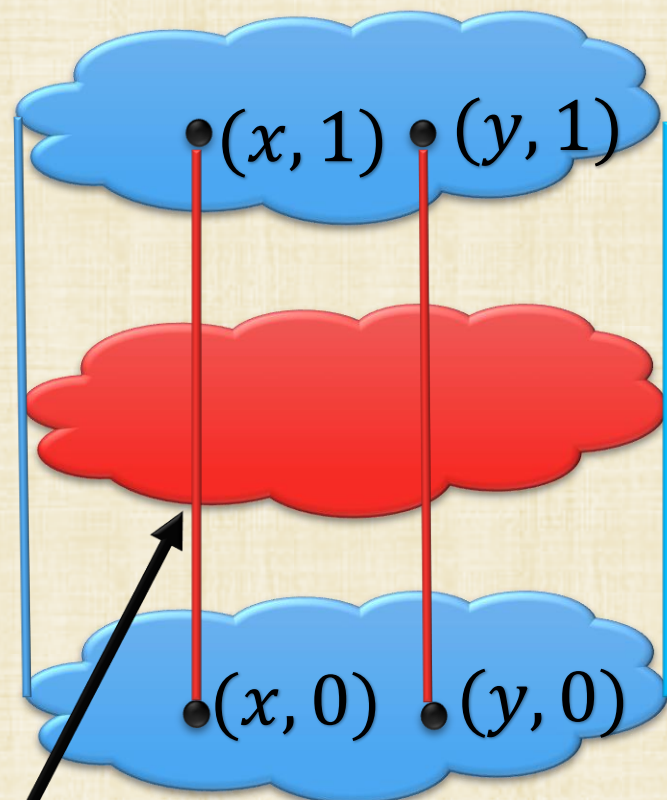
Geometric visualization of H

$X \times \{1\} \cong X$ →

$X \times \{t\} \cong X$ →

$X \times \{0\} \cong X$ →

$\{x\} \times I \cong I$ ↗

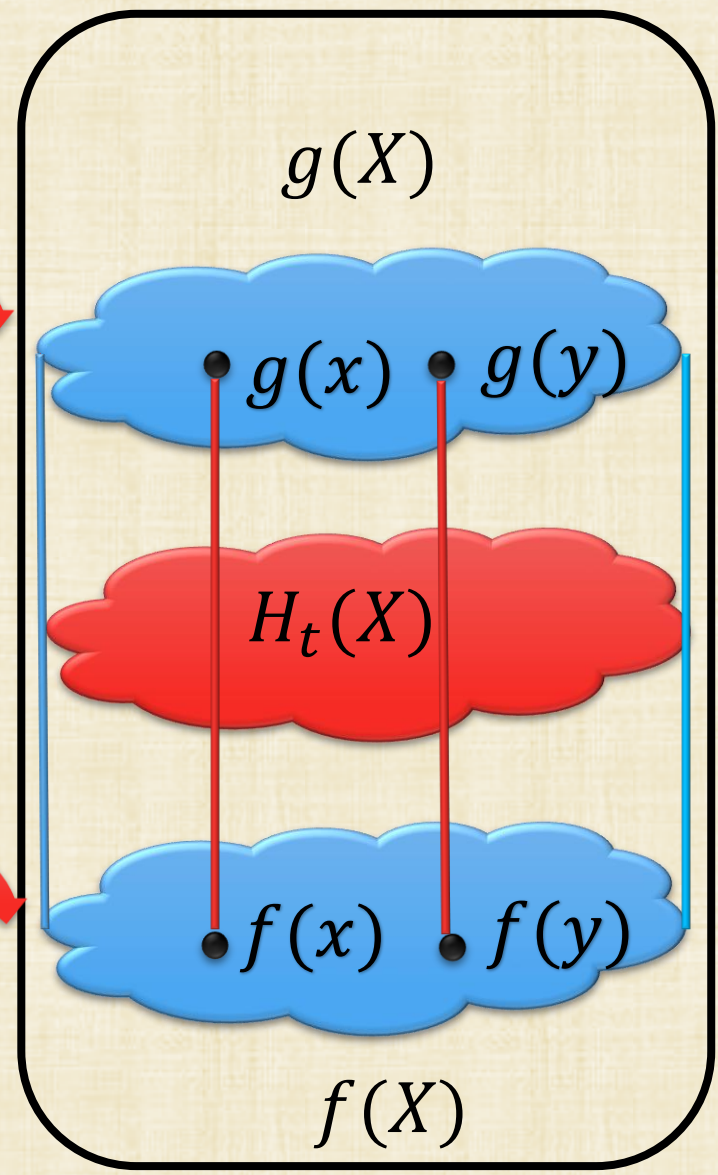


$X \times I$

g

f

Y



$g(X)$

$H_t(X)$

$f(X)$

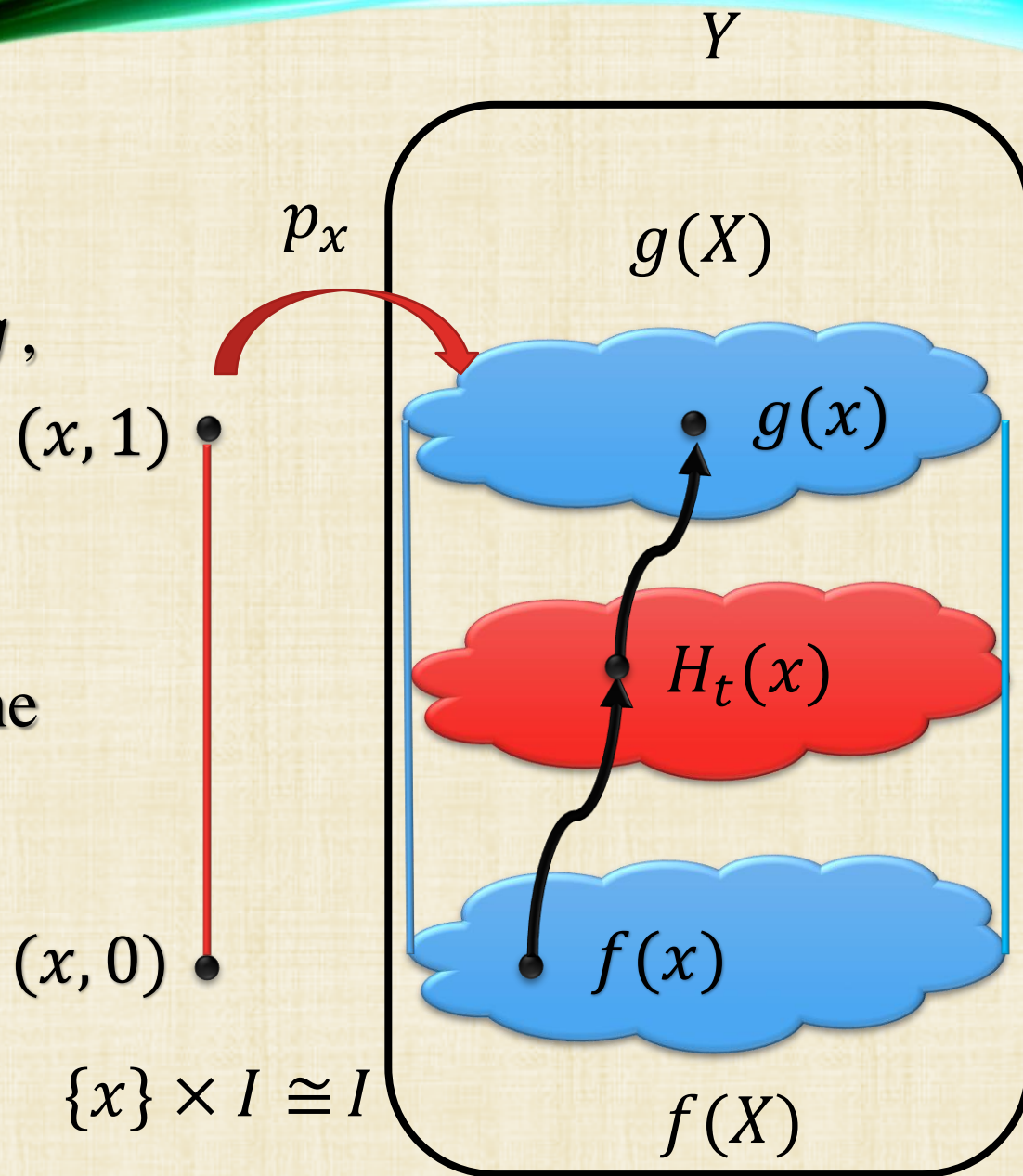
Geometric visualization of H

Fixed $x \in X$, the homotopy $H: f \simeq g$,
define a path $p_x: I \rightarrow Y$ as;

$$p_x(t) = H(x, t), \text{ for all } t \in I.$$

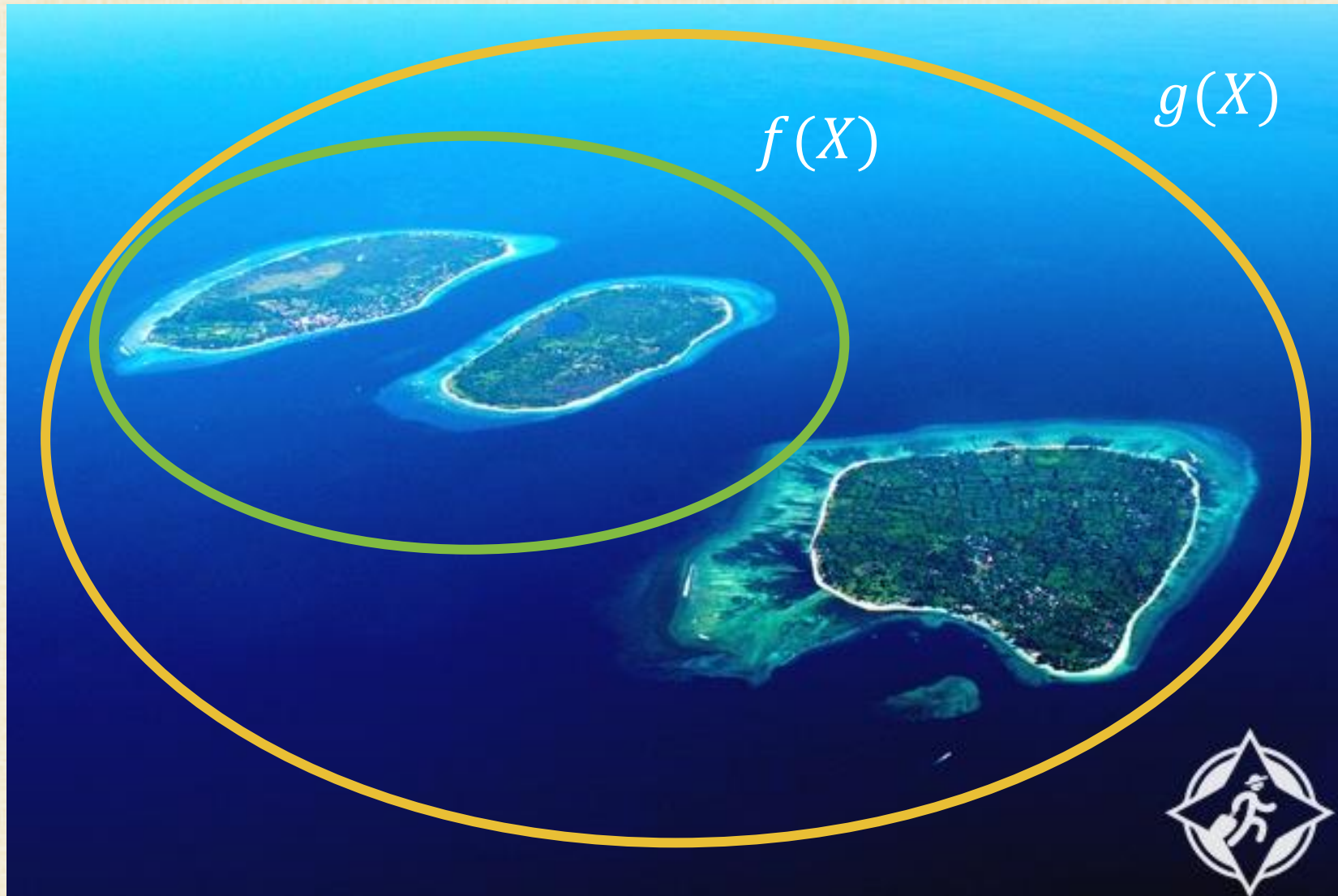
Notice that, p_x is a continuous map as the
following commutative diagram:

$$\begin{array}{ccc} I \xrightarrow{\cong} \{x\} \times I & \xrightarrow{i} & X \times I \\ & \searrow p_x & \downarrow H \\ & & Y \end{array}$$



In fact, $p_x(0) = f(x)$ and $p_x(1) = g(x)$.





Exercise:

The relation \simeq , is an equivalence relation on the set of all continuous maps from a topological space X into a topological space Y .

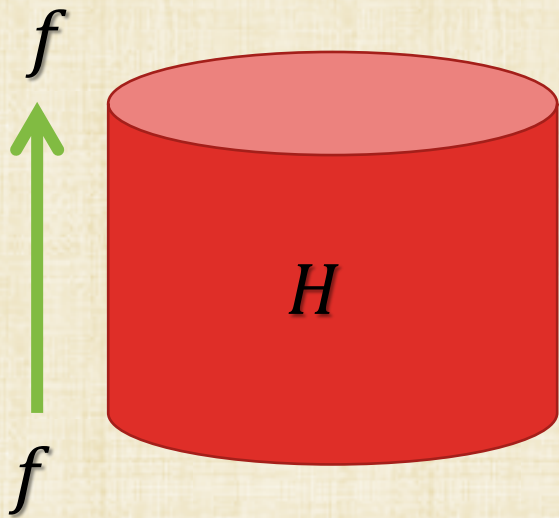
That is;

- ✓ \simeq is reflexive; ($H: f \simeq f$, defined as; $H(x, t) = f(x), \forall (x, t) \in X \times I$).
- ✓ \simeq is symmetric; (If $H: f \simeq g$, define $G: g \simeq f$ as; $G(x, t) = H(x, 1 - t), \forall (x, t) \in X \times I$), and;
- ✓ \simeq is transitive; ($H: f \simeq g$ and $G: g \simeq h$, define $F: f \simeq h$ as;

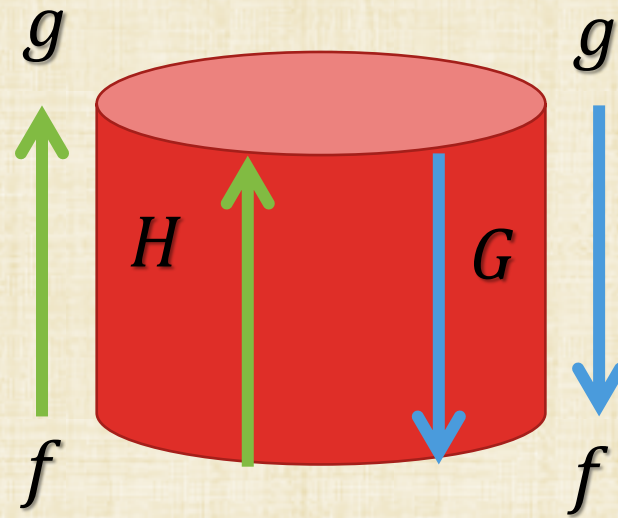
$$F(x, t) = \begin{cases} H(x, 2t); & 0 \leq t \leq \frac{1}{2} \\ G(x, 2t - 1); & \frac{1}{2} \leq t \leq 1 \end{cases}.$$

Due \simeq , the equivalence classes are called homotopy classes. Prof. Dr. Hana' M. Ali

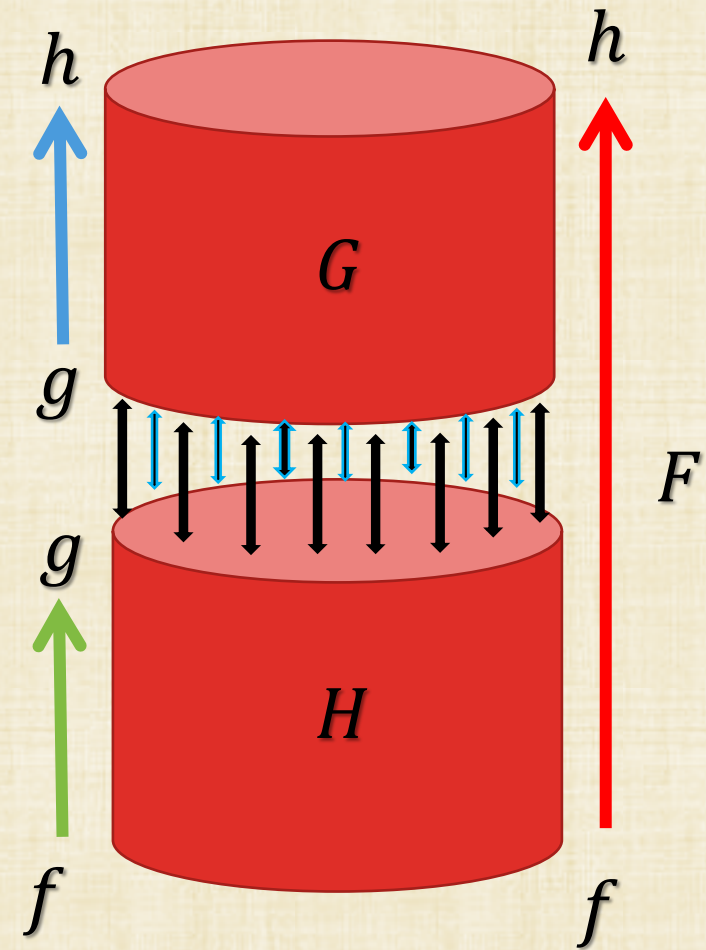
\simeq is reflexive



\simeq is symmetric



\simeq is transitive



Theorem:

The compositions of homotopic maps are homotopic.

Proof: Suppose we have the following continuous maps $f_1, f_2: X \rightarrow Y$ and $g_1, g_2: Y \rightarrow Z$ such that $H: f_1 \simeq f_2$ and $G: g_1 \simeq g_2$. Wanted,
 $g_1 \circ f_1 \simeq g_2 \circ f_2$.

Define $F: X \times I \rightarrow Z$ as;

$$F(x, t) = \begin{cases} g_1 \circ H(x, 2t); & 0 \leq t \leq \frac{1}{2}, \\ G(f_2(x), 2t - 1); & \frac{1}{2} \leq t \leq 1 \end{cases},$$

As a homework, show that F is continuous. In fact ;

$$F(x, 0) = g_1 \circ H(x, 0) = g_1 \circ f_1(x) \text{ and};$$

$$F(x, 1) = G(f_2(x), 1) = g_2 \circ f_2(x).$$

Examples:

1. Every two continuous maps $f, g: X \rightarrow \mathbb{R}^n$ from a topological space X into the Euclidean space \mathbb{R}^n are homotopic. In fact, $H: f \simeq g$ defined as:

$$H(x, t) = (1 - t) \cdot f(x) + t \cdot g(x), \text{ for all, } (x, t) \in X \times I.$$

2. If S is a convex subset of \mathbb{R}^n , then every two continuous maps $f, g: X \rightarrow S$ are homotopic.
3. If Y is indiscrete topological space (i.e. $T = \{\emptyset, X\}$), then every two maps $f, g: X \rightarrow Y$ are homotopic.

**Thank You
Very Much
For
Lessening**

