

## 2: Integrals of Vector Functions

### Definition (6):

The indefinite integral of  $r$  with respect to  $t$  is the set of all antiderivatives of  $r$ , denoted by  $\int r(t)dt$ . If  $R$  is any antiderivative of  $r$ , then

$$\int r(t)dt = R(t) + C.$$

### Definition (7):

If the components of  $r(t) = f(t)i + g(t)j + h(t)k$  are *integrable over*  $[a, b]$ , then *so is*  $r$ , and the definite integral of  $r$  from  $a$  to  $b$  is:

$$\int_a^b r(t)dt = \left(\int_a^b f(t)dt\right)i + \left(\int_a^b g(t)dt\right)j + \left(\int_a^b h(t)dt\right)k.$$

### Example (4):

Integrate vector function  $r(t) = (\cos t)i + j - 2tk$ .

### Solution:

$$\begin{aligned}\int r(t)dt &= \left(\int \cos t dt\right)i + \left(\int dt\right)j + \left(\int -2tdt\right)k \\ &= (\sin t)i + tj - t^2 k + C, \text{ where } C = c_1i + c_2j + c_3k.\end{aligned}$$

### Example (5):

Calculate  $\int_0^\pi [(\cos t)i + j - 2tk]dt$ .

### Solution:

$$\int_0^\pi [(\cos t)i + j - 2tk]dt = [\sin t]_0^\pi i + [t]_0^\pi j - [t^2]_0^\pi = \pi j - \pi^2 k.$$

### Note:

The Fundamental Theorem of Calculus for Continuous Vector Functions Says that:

$\int_a^b r(t)dt = [R(t)]_a^b = R(b) - R(a)$ , where  $R$  is any antiderivative of  $r$ , so that  $R'(t) = r(t)$ .

### Notes:

- 1: An antiderivative of a vector function is also a vector function.
- 2: A definite integral of a vector function is a single constant vector.

### Example (6):

Given acceleration vector  $a(t) = (-3 \cos t)i - (3 \sin t)j + 2k$ . Find the position vector  $r(t)$  such that  $v(0) = 3j$  and  $r(0) = 4i$ .

**Solution:**

$$a(t) = \frac{dv}{dt} = (-3 \cos t)i - (3 \sin t)j + 2k \rightarrow$$

$$v(t) = \int [(-3 \cos t)i - (3 \sin t)j + 2k] dt \\ = -3(\sin t)i + 3(\cos t)j + 2tk + C_1$$

$$\text{Since } v(0) = 3j \rightarrow 3j = 3j + C_1 \rightarrow C_1 = 0.$$

$$\therefore v(t) = -3(\sin t)i + 3(\cos t)j + 2tk$$

$$\therefore \frac{dr}{dt} = -3(\sin t)i + 3(\cos t)j + 2tk$$

$$\therefore r(t) = \int [-3(\sin t)i + 3(\cos t)j + 2tk] dt \rightarrow$$

$$r(t) = 3(\cos t)i + 3(\sin t)j + t^2k + C_2$$

$$\text{Since } r(0) = 4i \rightarrow 4i = 3i + C_2 \rightarrow C_2 = i.$$

$\therefore$  The position vector is:

$$r(t) = (1 + 3 \cos t)i + (3 \sin t)j + t^2k.$$