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Evanescent field optimization on Y-branch silicon nitride optical waveguide for biosensing



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ABSTRACT

Evanescent field had been widely used in bio and chemical sensors. However in most cases, evanescent field is not maximized and consequently produced an unoptimized sensor performance. It is the aim of the paper to optimize the design of 1:2 Y-branch splitter optical waveguide through simulation by using FD-BPM. Y-branch splitter are simulated to optimize the power loss. Width of waveguide and effective angle are manipulated in the power loss optimization. The result shows that evanescent field is maximized at optimized thickness and width. The result suggests that Y-branch splitter with width of 25 μ m and effective angle of 6.24° is the best design for evanescent field sensor application with both high sensitivity and signal to noise ratio.

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1. Introduction

Waveguide based bio and chemical sensors, utilizing evanescent field have attracted a lot of attention in the past decade due to its versatility and advantages. Some of the major advantages are its simplicity, robustness and label-free measurement [1]. A lot of research has been conducted on waveguide configurations namely, linear and Y-branch for creating integrated optics for various applications. However, in the literature so far, there are only optimization of linear waveguides; both in simulation and experimental for various applications including biosensors [2-4]. Although usage of Y-branch in integrated optics sensors has been implemented [5,6], direct optimization of Y-branch optical waveguide had been limited to only in optical communications [7-9].

Therefore, in this work we proposed a direct optimization of Y-branch to be used for biosensor application via enhanced evanescent field penetration and minimal power loss. Finite difference beam propagation method (FD-BPM) is used in this paper to provide 3D optical waveguide structure with high non-linearity such as bending and tapering [10]. Y-branch splitter is used in this context as evanescent field sensor with one of the output branch served as sensing site and the other as reference [11]. Hence, the difference between output power can be detected directly and instantly which is advantageous compared to linear waveguide

that is used in Ref. [12-14].

2. Methodology

Fig. 1(a) illustrated the scattering of evanescent excitation binding of analyte on the waveguide surface. Y-branch splitter, as illustrated in Fig. 1(b), is simulated and designed with the aim of minimizing power loss. TE polarization with wavelength of 1.064 μ m is used in Y-branch simulation with thickness and width of 0.1 μ m and 4 μ m respectively. Refractive index of cladding, waveguide and substrate layer is 1.33, 1.98 and 1.45 which correspond to water, silicon nitride and silicon oxide respectively.

$$\theta_{eff} = 2 \times \tan^{-1} \frac{(X_{off}/2)}{L_{off}}$$
⁽¹⁾

Y-branch splitter is constructed in the simulation software by using bending waveguide structure with input waveguide width to be twice the size of branch waveguide. X_{off} , L_{off} and θ_{eff} are the parameters that characterize Y-branch splitter (see Fig. 1(c)). X_{off} is the distance between two output branches, L_{off} is the horizontal distance of bending waveguide and θ_{eff} is effective angle of Y-branch splitter which is related to X_{off} and L_{off} as shown in Eq. (1).

Simulation of Y-branch splitter with variation of start location of bending waveguide for mode conversion loss enhancement is known as location optimization. Start location is varied from $205 \,\mu$ m to $155 \,\mu$ m with step of $5 \,\mu$ m in simulation of location



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Fig. 1. (a) Scattering of evanescent excitation binding of analyte on the waveguide surface; (b) Y-branch splitter used as evanescent field biosensor; (c) Model of Y-branch splitter without taper.

optimization. The range of L_{off} used in investigation of Y-branch splitter are from 300 to 2100 μ m with step of 200 μ m and result in θ_{eff} that is in the range of approximately 3–22°. As the L_{off} increases, θ_{eff} and slope of bending waveguide reduces while length of bending waveguide increases. Simulation is repeated to perform location optimization to maximize the power output (*Pout*) at each effective angle. The simulation is followed by the increment of the width of Y-branch splitter from 4 μ m to 10 μ m with location optimization. This is due to the fact that more power can be confined in the waveguide and thus theoretically, it can reduced the bending loss of the waveguide structure. Width of the waveguide is further increased to 15 μ m, 20 μ m and 25 μ m without location optimization so that relation of width to output power can be further investigated.

3. Results and discussion

Fig. 2(a) shows the result of *Pout* as a function of effective angle for Y-branch splitter with input width of 8 μ m and branching width is 4 μ m. It can be seen that location optimization increases *Pout* significantly, especially at smaller θ_{eff} . *Pout* profile of Y-branch splitter increased gradually as effective angle is increased to a peak at 13.68° followed by a rapid decrement with larger angles. *Pout* profile is mainly affected by the bending loss which is in turn affected by the effective angles. Gradual increment of *Pout* is caused by the optimized effective angle which resulted in optimized branching angle and length of bending waveguide. In return, rapid decrement of the *Pout* is caused by shorter length of the bending waveguide with rapid increment of rate of the bending loss.

Fig. 2(b) shows the result of *Pout* as function of the effective angle for input width of 20 μ m with and without location optimization. It can be seen that increment of *Pout* caused by location optimization is insignificant for width of 10 μ m (or input width of 20 μ m). This is due mainly to the increasing number of mode as width increases and thus the mode beating profile changes in input waveguide as shown in Figs. 3(a) and (b). Due to this reason, location optimization is not performed in Y-branch splitter with bigger input width than 20 μ m.

Fig. 3(c) shows the *Pout* as function of effective angle for input width of 8 μ m, 20 μ m, 40 μ m and 50 μ m. It can be seen that the increment of *Pout* for input of 20 μ m from 8 μ m is significant whereby *Pout* is increased by 19.7%. The increment is mainly due to the better power confinement in the bending waveguide and thus the bending loss is reduced regardless of effective angle. However, increment of *Pout* become smaller as input width is



Fig. 2. (a) *Pout* as function of effective angle with and without location optimization for input width of 8 μm; (b) *Pout* as function of effective angle with and without location optimization for input width of 20 μm.



Fig. 3. (a) Mode beating profile of input waveguide for width of 10 μm; (b) 4 μm respectively; (c) *Pout* as function of effective angle for input width of 8 μm, 20 μm, 30 μm, 40 μm and 50 μm. Location optimization is performed only on Y-branch with input width of 8 μm and 20 μm.

further increased to $30 \,\mu\text{m}$, $40 \,\mu\text{m}$ and $50 \,\mu\text{m}$. *Pout* increment is caused by reducing bending loss and increased power transmission at coupling of laser source. On the other hand, *Pout* increment is limited by maximum power transmitted from input waveguide into bending waveguide since power in input waveguide is increased by 1.33% only with width of waveguide doubled. As a result, *Pout* is almost saturated by optimization of bending loss after the input width is increased to $20 \,\mu\text{m}$ and further increment of width increases *Pout* by slight increment of power in input waveguide. At input width of $50 \,\mu\text{m}$, the maximum *Pout* is 0.045 W.

4. Conclusion

Y-branch splitter with optimized evanescent field and minimum power loss has been designed to improve sensitivity and signal to noise ratio of the biosensor. The output power was found to reach its maximum at effective angle of 13.68°. For larger angles, the Y-branch splitter suffered severe bending loss. However, it had also been found that the output power was reduced further with smaller width. This decrement is mainly due to the longer length of bending waveguide that suffers bending loss. Bigger widths of bending waveguide showed better power confinement and subsequently reduced the bending loss. The results showed that Y-branch splitter required the waveguide width of 25 μ m in order to reach the optimum power of 0.045 W. Results in this paper suggested that Y-branch splitter of 25 μ m width, effective angle of 6.24° and thickness of 0.1 μ m to be the direct optimum design for evanescent field sensor application with both high sensitivity and signal to noise ratio.

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